Imaging of Construction Materials and Geomaterials

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On the Use of Digital Volume Correlation for the Identification of the Crushing Behavior of Plaster

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Plasterboard

Paper Roller coating

Foamed plaster (core)



1.4 mm



Brittle Foam





Multiscale Microstructure







LO1





Nail Pull Test on Plasterboard



[ASTM Standard C1396/C1396M-14, 2014, DOI: 10.1520/C1396_C1396M]



Nail Pull Test on Plasterboard





In-Situ Nail Pull Test



[Bouterf et al., 2016, Exp. Mech. DOI: 10.1007/s11340-016-0168-8]









300

(X) 200 Toaq

100

0

ĨN.

g





300

(Z) 200 Toaq

100

0

g





300

(Z) 200 Toaq

100

0

g





300

(X) 200 Toaq

100

0

g.





300

(Z) 200 Togo

100

0

g





300 g

(X) 200 Toaq

100

0





300

(X) 200 Toaq

100

0

g





300

(X) 200 Toaq

100

0

g





300

(X) 200 Toaq

100

0

g







(X) 200 Toaq

100

0

g







Spherical Indentation Test

• Aims

- Better understand crushing mechanism
- Identify local failure criterion
- Sample









Tomographic Observations

Tomographic observations

- Compaction accompanied by pore collapse
- Same observations in artificial porous rock*



*[Leite et al., 2001, Eng. Geol., 59 pp. 267-280]

Spherical Indentation Test

Identification of local failure criterion

- Estimation of multiaxial stress state in transition zone





Two-Phase Model









$$a^{2} = \begin{cases} 2Rd - d^{2} \\ 2\rho\delta - \delta^{2} \end{cases} \quad \phi = \frac{V_{i}}{V_{0}} = \frac{\pi Rd^{2} - d^{3}/3}{\pi \rho\delta^{2} - \delta^{3}/3} \end{cases}$$

Scan	g	h	i	j
d / δ	0.44	0.47	0.50	0.46

 $\phi \approx 0.47$ $\Delta \varepsilon_{CE} = \log(1-\phi) \approx -0.63$





Static Analysis

No shear flow (surface normal = eigen stress direction)

$$F_z = \pi a^2 \sigma_R$$











Digital Volume Correlation (DVC)

Gray level (reconstructed) volumes

 $f(\underline{x}) = g(x)$

- Conservation of gray levels
 - $f(\underline{x}) \cong g(\underline{x} + \underline{u}(\underline{x}))$
- Measure $\underline{u}(\underline{x})$?



Digital Volume Correlation

- Local registration:
 - Biomechanics
 [Bay et al., 1999; 2002; Verhulp et al., 2004; Tong et al., 2009...]
 - Mechanics of materials
 [Bornert et al., 2004; Franck et al., 2007; Germaneau et al., 2007; Lenoir et al., 2007; Forsberg et al., 2008...]
- Global registration:
 - Biomechanics [Benoit *et al.*, 2009; Madi *et al.*, 2013]
 - Mechanics of materials
 [Roux et al., 2008; Réthoré et al., 2008; HF et al., 2009; Limodin et al., 2009...]

Global Approach to DVC

- Select a specific displacement basis $\underline{\varphi}_i(\underline{x})$ such that

$$\underline{u}(\underline{x}) = \sum_{i} a_{i} \underline{\varphi}_{i}(\underline{x})$$

- Minimize correlation residuals* $\rho_c^2(\{a_i\}) = \iiint [f(\underline{x}) - g(\underline{x} + a_i \underline{\varphi_i}(\underline{x}))]^2 d\underline{x}$
- Successive linearizations / corrections

$$M_{ij}\delta a_j = b_i$$

Finite Element DVC

$$\rho_{\text{lin}}^{2}(\delta \underline{u}) = \int_{\Omega} [f(\underline{x}) - \hat{g}(\underline{x}) - (\delta \underline{u} \cdot \nabla f)(\underline{x})]^{2} d\underline{x}$$

$$= \sum_{e} \int_{\Omega_{e}} [f(\underline{x}) - \hat{g}(\underline{x}) - \delta a_{i}^{e} (\underline{\varphi}_{i} \cdot \nabla f)(\underline{x})]^{2} d\underline{x}$$

Elementary matrix and vector (e.g., C8P1*)

$$M_{ij}^{e} = \int_{\Omega_{e}} \left(\nabla f \cdot \underline{\varphi}_{i} \right) (\underline{x}) \left(\nabla f \cdot \underline{\varphi}_{j} \right) (\underline{x}) d\underline{x}$$
$$b_{i}^{e} = \int_{\Omega_{e}} \left[f(\underline{x}) - \hat{g}(\underline{x}) \right] \left(\nabla f \cdot \underline{\varphi}_{i} \right) (\underline{x}) d\underline{x}$$

*[Roux et al., 2008, Comp. Part A 39 pp. 1253-1265]

C8-DVC Analyses

Small amplitude displacements

- Standard displacement resolution \approx 0.4 voxel (ℓ = 8 voxels)
- Unreliable elastic strain estimates





Reduced Kinematic Basis

FE-generated kinematic basis

- Isotropic elasticity
- Crushed zone excluded
- T4 mesh
- Dirichlet boundary conditions
 - measured rigid body motion (C8-DVC)
 - linear combination of modes



Reduced Kinematic Basis

- BCs under crushed zone
 - Axisymmetric fields

 $u_x(a_i, \varphi, \theta) = v \cos(\varphi) \sin(\theta) + w \cos(\varphi) \cos(\theta)$ $u_y(a_i, \varphi, \theta) = v \sin(\varphi) \sin(\theta) + w \sin(\varphi) \cos(\theta)$ $u_z(a_i, \varphi, \theta) = v \cos(\varphi) - w \sin(\theta)$ $\theta \text{ and } \varphi \text{ are polar et azimuthal angles}$ $v = a_1 + a_2 \cos(\theta) + a_3 \cos(2\theta) + a_4 \cos(3\theta)$ $w = a_5 \sin(\theta) + a_6 \sin(2\theta) + a_7 \sin(3\theta)$

Shear fields
 'unperfect' loading



Reduced Kinematic Basis



Rigid body motion



Displacement field associated with 1st amplitude



Displacement field associated with 8th amplitude

[Bouterf et al., 2014, Strain 50 pp. 444-453]

Measurement Results

- Standard displacement resolution ≈ 0.02 voxel ($\ell = 8$ voxels)
 - Divided by 20 wrt. standard C8-DVC
 - # DOF = 9



Comparison



RMS GL residual: 5.06%

46

RMS GL residual: 5.14%







50 Minor Principal Stress 10 50 z



Surface Contour $\sigma_3 = -5$ MPa





Surface Contour $\sigma_3 = -6$ MPa





Surface Contour $\sigma_3 = -7$ MPa









FE Simulations

Good macroscopic agreement





Abrupt / smooth transition



Outlook: Cracks (of course)!

1.8

1.6

1.4

1.2

1.0

0.8

0.6 0.4

0.2

0





'Here is my secret. It is very simple: It is only with the heart that one can see rightly; What is essential is invisible to the eye.'

